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Analytic and numeric analysis for deformation of non-prismatic beams resting on elastic foundations

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Abstract

Background: The buckling load as well as the natural frequency under axial load for non-prismatic beam is a changeling problem. Determination of buckling load, natural frequency, and elastic deflection is very important in civil applications. The current paper used both perturbation method (PM), analytic method, and differential quadrature method (DQM), numerical method, to find buckling load and natural frequency with different end supports. The deflection of the beam resting on an elastic foundation under transverse distributed and axial loads is also obtained. Both PM and DQM are used for non-prismatic beams with rectangular and circular cross sections in the vibration analysis. The comparisons of results obtained from both PM and DQM showed perfect agreement with analytical solution for uniform beams with different end supports. The PM and DQM succeeded powerfully for investigating the buckling load as well as the natural frequency for non-prismatic beam.

Results: The percentage of relative error between DQM and PM doesn't exceed than 5% if the gradient of rectangular section height and the gradient of circular section radius are less than 0.6. As the gradient of height and radius increase, the maximum deflection decreases and the location of maximum deflection displaced toward the smaller moment of inertia.

Conclusions: The PM has not been used for solving the problem of non-prismatic beams resting on elastic foundations subjected to transverse distributed and axial loads. The current research proved the good ability of PM as an analytical solution for a complicated problem and defined its range of accuracy as compared to DQM. Also, it introduced accurate empirical formulae to find both natural frequency and buckling load of non-prismatic beams. These empirical formulae represent a good achievement in vibration analysis of non-prismatic beams.

Keywords: Non-prismatic beams, Elastic foundation, Perturbation method, Differential quadrature method

1 Background

The DQM is a numerical technique for initial and/or boundary value problems. It was developed by the late Richard Bellman and his associates in the early 70 s and, since then, the method has been successfully employed in a variety of problems in physical and engineering sciences. The DQM has been projected by its proponents

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as a potential alternative to the conventional numerical solution techniques such as the finite difference and finite element methods [1]. Non-prismatic beams resting on elastic foundations are important structural elements. The dynamic characteristics of such non-prismatic beams are of considerable importance in many designs. The vibration of non-prismatic beams is formulated as a fourth-order differential equation of variable coefficients; it is possible to determine their exact solutions [2, 3], using homotopy analysis [2] or the Green's functions method [3]. However, in most cases, the solution



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is obtained by approximate methods such as finite difference [4], DQM [5], boundary element method [6], the power series [7, 8], Lagrange multiplier formulation [9], coupled displacement field method [10]. Sato [11] reported the transverse vibration of linearly tapered beams using Ritz method. He studied the effect of end restraints and axial load on the natural frequencies.

The PM is a method which relies on there being a dimensionless parameter in the problem that is relatively small: $\varepsilon < <1$. The PM is used to analyze the nonlinear vibration behavior of imperfect general structures under static load. The effects on the linearized and nonlinear vibrations caused by geometric imperfections, a static fundamental state, and a nontrivial static state are included in the perturbation procedure. The theory is applied in the nonlinear vibration analysis of cylindrical shells [12]. However, the PM has not been used for solving the problem of non-uniform beams resting on elastic foundations under the action of transverse distributed load and axial load. In this paper, the PM is used to obtain the non-dimensional frequencies and buckling loads for a non-prismatic beam resting on elastic foundations. Also, the deflected shape can be obtained by PM.

In the present paper, the concepts of both DQM and PM are presented for the vibration analysis of non-prismatic Euler–Bernoulli beam. The DQM was widely used in vibration analysis of non-prismatic beams. In this paper, we used it again to solve the same problem to investigate accuracy of PM in analysis of vibration of non-prismatic beams. The generated PM results for non-prismatic beam also verified with Dua [13]. From the comparison between PM and DQM, an empirical formula is investigated to find natural frequency and buckling load of non-prismatic beams. These empirical formulae represent a good achievement in vibration analysis of non-prismatic beams. A full parametric study is then performed.

Figure 1 shows the schematic diagram for non-prismatic beam on elastic foundation subjected to axial load "n" and transverse uniform load p(x). The free vibration of a non-uniform beam is governed by the following equation

$$\frac{\partial^2}{\partial x^2} \left(\text{EI}(x) \frac{\partial^2 Y}{\partial x^2} \right) - \rho A(x) \omega^2 Y + n \frac{\partial^2 Y}{\partial x^2} + kY = p(\mathbf{x})$$

Using the non-dimensional parameters: $W = \frac{Y}{L}$, $X = \frac{x}{L}$, $Q = \frac{nL^2}{EI_0}$, $K = \frac{kL^4}{EI_0}$, $P = \frac{p(x)L^2}{EI_0}$, $\Omega^4 = \frac{\rho A(x)L^4 \omega^2}{EI_0}$, and $S(X) = \frac{EI(x)}{EI_0}$.

Equation (1) by direct substitution will be reduced to

$$S(X) \cdot \frac{d^4 W}{dX^4} + 2 \frac{dS(X)}{dX} \cdot \frac{d^3 W}{dX^3} + \frac{dS^2(X)}{dX^2} \cdot \frac{d^2 W}{dX^2} + Q \frac{d^2 W(X)}{dX^2} + \left(K - \Omega^4\right) \cdot W = P$$
(2)

where W is non-dimensional transverse deflection, X is non-dimensional position along beam length, Q is non-dimensional axial load parameter, K is linear non-dimensional stiffness of elastic foundation parameter, P is non-dimensional transverse distributed load, Ω is non-dimensional frequency parameter, I_0 is the base mass moment of inertia, and S(X) is non-dimensional stiffness parameter of the beam.

In the current paper, the beam has a rectangular cross section of linear variable height and constant width. The height is h_0 at the base and h_1 at the end. The equations of non-dimensional height, non-dimensional cross section, and non-dimensional stiffness parameters are:

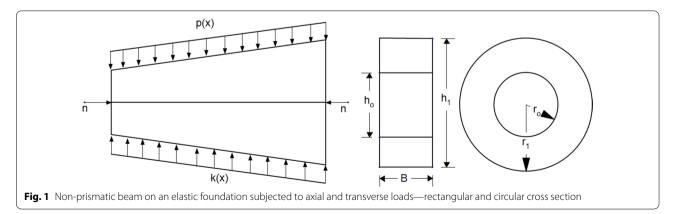
$$H(X) = (1 + \gamma X)$$

$$A(X) = A_{o}(1 + \gamma X)$$

$$S(X) = (1 + \gamma X)^{3}$$

Where : $\gamma = \frac{h_{1} - h_{o}}{h_{o}}$
(3)

Another case is considered for a beam of circular cross section of linear variable radius. The equations of nondimensional radius, non-dimensional cross section, and non-dimensional stiffness parameters are:



$$R(X) = (1 + \gamma X)$$

$$A(X) = A_{o}(1 + \gamma X)^{2}$$

$$S(X) = (1 + \gamma X)^{4}$$
(4)
Where : $\gamma = \frac{R_{1} - R_{o}}{R_{o}}$

2 Methods

2.1 Perturbation method (PM)

as perturbation parameter ε

The PM is employed for rectangular cross section as:

$$S(X) = 1 + 3\gamma X + 3\gamma^{2} X^{2} + \gamma^{3} X^{3}$$

$$\frac{dS}{dX} = 3\gamma + 6\gamma^{2} X + 3\gamma^{3} X^{2}$$
(5)
$$\frac{d^{2}S}{dX^{2}} = 6\gamma^{2} + 6\gamma^{3} X$$

$$S(X) = 1 + 4\gamma X + 6\gamma^{2} X^{2} + 2\gamma^{3} X^{3} + \gamma^{4} X^{4}$$

$$\frac{dS}{dX} = 4\gamma + 12\gamma^{2} X + 6\gamma^{3} X^{2} + 4\gamma^{4} X^{3}$$
(6)
$$\frac{d^{2}S}{dX^{2}} = 12\gamma^{2} + 12\gamma^{3} X + 12\gamma^{4} X^{2}$$

By substituting Eqs. (5, 6) in Eq. (2) and considering γ

where $0 \le \varepsilon \le 1$.

The solution will be presented for non-uniform rectangular cross section; for zero-order perturbation,

$$\frac{d^4 W_{\rm o}}{dX^4} + Q \frac{d^2 W_{\rm o}}{dX^2} + \left(K - \Omega^4\right) W_{\rm o} = P_{\rm o}$$
(9)

For first-order perturbation,

$$\frac{d^4 W_1}{dX^4} + Q \frac{d^2 W_1}{dX^2} + \left(K - \Omega^4\right) W_1$$

= $-3X \frac{d^4 W_0}{dX^4} - 6 \frac{d^3 W_0}{dX^3} + \Omega^4 X W_0$ (10)

For second-order perturbation,

$$\frac{d^4 W_2}{dX^4} + Q \frac{d^2 W_2}{dX^2} + \left(K - \Omega^4\right) W_2$$

= $-6 \frac{d^2 W_0}{dX^2} - 12X \frac{d^3 W_0}{dX^3} - 3X^2 \frac{d^4 W_0}{dX^4}$ (11)
+ $\Omega^4 X W_1 - 6 \frac{d^3 W_1}{dX^3} - 3X \frac{d^4 W_1}{dX^4}$

For third-order perturbation,

$$\begin{pmatrix} 1 + 3\varepsilon X + 3\varepsilon^2 X^2 + \varepsilon^3 X^3 \end{pmatrix} \frac{d^4}{dX^4} \left(W_0 + \varepsilon W_1 + \varepsilon^2 W_2 + \varepsilon^3 W_3 + \cdots \right) \\ + 2 \left(3\varepsilon X + 6\varepsilon^2 X + 3\varepsilon^3 X^2 \right) \frac{d^3}{dX^3} \left(W_0 + \varepsilon W_1 + \varepsilon^2 W_2 + \varepsilon^3 W_3 + \cdots \right) \\ + \left(6\varepsilon^2 + 6\varepsilon^3 X \right) \frac{d^2}{dX^2} \left(W_0 + \varepsilon W_1 + \varepsilon^2 W_2 + \varepsilon^3 W_3 + \cdots \right) \\ + Q \frac{d^2}{dX^2} \left(W_0 + \varepsilon W_1 + \varepsilon^2 W_2 + \varepsilon^3 W_3 + \cdots \right) \\ + \left(K - \Omega^2 (1 + \varepsilon X) \right) \left(W_0 + \varepsilon W_1 + \varepsilon^2 W_2 + \varepsilon^3 W_3 + \cdots \right) \\ = \left(P_0 + \varepsilon P_1 + \varepsilon^2 P_2 + \varepsilon^3 P_3 + \cdots \right)$$

$$(7)$$

$$\begin{pmatrix} 1 + 4\varepsilon X + 6\varepsilon^2 X^2 + 2\varepsilon^3 X^3 + \varepsilon^4 X^4 \end{pmatrix} \frac{d^4}{dX^4} \Big(W_0 + \varepsilon W_1 + \varepsilon^2 W_2 + \varepsilon^3 W_3 + \varepsilon^4 W_4 + \cdots \Big) \\ + 2\Big(4\varepsilon + 12\varepsilon^2 X + 6\varepsilon^3 X^2 + 4\varepsilon^4 X^3 \Big) \frac{d^3}{dX^3} \Big(W_0 + \varepsilon W_1 + \varepsilon^2 W_2 + \varepsilon^3 W_3 + \varepsilon^4 W_4 + \cdots \Big) \\ + \Big(12\varepsilon^2 + 12\varepsilon^3 X + 12\varepsilon^4 X^2 \Big) \frac{d^2}{dX^2} \Big(W_0 + \varepsilon W_1 + \varepsilon^2 W_2 + \varepsilon^3 W_3 + \varepsilon^4 W_4 + \cdots \Big) \\ + Q \frac{d^2}{dX^2} \Big(W_0 + \varepsilon W_1 + \varepsilon^2 W_2 + \varepsilon^3 W_3 + \varepsilon^4 W_4 + \cdots \Big) + \Big(K - \Omega^2 (1 + \varepsilon X) \Big) \Big(W_0 + \varepsilon W_1 + \varepsilon^2 W_2 + \varepsilon^3 W_3 + \cdots \Big) \\ = \Big(P_0 + \varepsilon P_1 + \varepsilon^2 P_2 + \varepsilon^3 P_3 + \varepsilon^4 P_4 + \cdots \Big)$$

$$\tag{8}$$

$$\frac{d^4 W_3}{dX^4} + Q \frac{d^2 W_3}{dX^2} + \left(K - \Omega^4\right) W_3
= -6X \frac{d^2 W_0}{dX^2} - 6X^2 \frac{d^3 W_0}{dX^3} - X^3 \frac{d^4 W_0}{dX^4}
- 6 \frac{d^2 W_1}{dX^2} - 12X \frac{d^3 W_1}{dX^3} - 3X^2 \frac{d^4 W_1}{dX^4}
+ \Omega^4 X W_2 - 6 \frac{d^3 W_2}{dX^3} - 3X \frac{d^4 W_2}{dX^4}$$
(12)

The left-hand side of Eqs. (8–12) is the same ordinary differential equation and its complementary solution is:

$$W_{i_{C}} = C_{i1} \cosh(m_{1}X) + C_{i2} \sinh(-m_{1}X) + C_{i3} \cosh(m_{2}X) + C_{i4} \sinh(-m_{2}X)$$
(13)

where C_{i1} , C_{i2} , C_{i3} , C_{i4} are constants, i = 0, 1, 2, 3 and

$$m_{1} = \sqrt{\frac{-Q + \sqrt{Q^{2} - 4(K - \Omega^{4})}}{2}}$$

$$m_{2} = \sqrt{\frac{-Q - \sqrt{Q^{2} - 4(K - \Omega^{4})}}{2}}$$
(14)

Assuming that the transverse load is a sine load across the beam length, the particular solutions for zero and first order are:

$$W_{\rm op} = \frac{P_{\rm o} \sin{(\pi X)}}{\pi^4 - Q\pi^2 + (K - \Omega^4)}$$
(15)

$$W_{1p} = \phi_{13} e^{m_1 X} + \phi_{14} e^{-m_1 X} + \phi_{15} e^{m_2 X} + \phi_{16} e^{-m_2 X} + \phi_{17} \cos(\pi x) + \phi_{18} x \sin(\pi x)$$
(16)

where

$$\begin{split} \phi_{13} &= \left(c_{01} + c_{11}f_{1}(x)\right), \phi_{14} = \left(c_{02} + c_{12}f_{2}(x)\right), \phi_{15} = \left(c_{03} + c_{13}f_{3}(x)\right) \\ \phi_{16} &= \left(c_{04} + c_{14}f_{4}(x)\right), \phi_{17} = f_{5}, \phi_{18} = f_{6} \\ f_{1}(x) &= A\left[\left(\Omega^{4} - 3m_{1}^{4}\right)\frac{x^{2}}{2} - 6m_{1}^{3}x\right] \\ &+ \left[\frac{-A}{2m_{1}} + \frac{2m_{2}C}{m_{1}^{2} - m_{2}^{2}}\right]\left[\left(\Omega^{4} - 3m_{1}^{4}\right)x - 6m_{1}^{3}\right] + \left[\frac{A}{4m_{1}^{2}} - \frac{4m_{1}m_{2}C}{\left(m_{1}^{2} - m_{2}^{2}\right)^{2}}\right]\left[\left(\Omega^{4} - 3m_{1}^{4}\right)\right] \\ f_{2}(x) &= -A\left[\left(\Omega^{4} - 3m_{1}^{4}\right)\frac{x^{2}}{2} - 6m_{1}^{3}x\right] \\ &+ \left[\frac{-A}{2m_{1}} + \frac{2m_{2}C}{m_{1}^{2} - m_{2}^{2}}\right]\left[\left(\Omega^{4} - 3m_{1}^{4}\right)x - 6m_{1}^{3}\right] + \left[\frac{-A}{4m_{1}^{2}} - \frac{4m_{1}m_{2}C}{\left(m_{1}^{2} - m_{2}^{2}\right)^{2}}\right]\left[\left(\Omega^{4} - 3m_{1}^{4}\right)\right] \\ f_{3}(x) &= C\left[\left(\Omega^{4} - 3m_{1}^{4}\right)\frac{x^{2}}{2} - 6m_{1}^{3}x\right] \\ &+ \left[\frac{-C}{2m_{2}} + \frac{-2m_{1}A}{m_{1}^{2} - m_{2}^{2}}\right]\left[\left(\Omega^{4} - 3m_{1}^{4}\right)x - 6m_{1}^{3}\right] + \left[\frac{C}{4m_{2}^{2}} + \frac{4m_{1}m_{2}A}{\left(m_{1}^{2} - m_{2}^{2}\right)^{2}}\right]\left[\left(\Omega^{4} - 3m_{1}^{4}\right)\right] \\ f_{4}(x) &= -C\left[\left(\Omega^{4} - 3m_{1}^{4}\right)\frac{x^{2}}{2} - 6m_{1}^{3}x\right] \\ &+ \left[\frac{-C}{2m_{2}} + \frac{-2m_{1}A}{m_{1}^{2} - m_{2}^{2}}\right]\left[\left(\Omega^{4} - 3m_{1}^{4}\right)x - 6m_{1}^{3}\right] + \left[\frac{C}{4m_{2}^{2}} + \frac{4m_{1}m_{2}A}{\left(m_{1}^{2} - m_{2}^{2}\right)^{2}}\right]\left[\left(\Omega^{4} - 3m_{1}^{4}\right)\right] \\ f_{5} &= \frac{4m_{1}\pi}{\left(m_{1}^{2} - m_{2}^{2}\right)} + \frac{4m_{2}\pi}{\left(m_{2}^{2} - \pi^{2}\right)^{2}} + \frac{6P_{0}\pi^{3}}{\pi^{4} - Q\pi^{2} + \left(K - \Omega^{4}\right)} \\ f_{6} &= \frac{6P_{0}}{\pi^{4} - Q\pi^{2} + \left(K - \Omega^{4}\right)}\left(\Omega^{4} - 3\pi^{4}\right)\left[\frac{-2m_{1}}{m_{1}^{2} + \pi^{2}} + \frac{-2m_{2}}{m_{2}^{2} + \pi^{2}}\right] \\ A &= \frac{1}{2m_{1}\left(m_{1}^{2} - m_{2}^{2}\right)} \\ C &= \frac{1}{2m_{2}\left(m_{2}^{2} - m_{1}^{2}\right)} \end{aligned}$$

$$W_{2p} = \frac{1}{k - \Omega^4} \begin{cases} \left(u_1 - Q \left(u_1'' + 2m_1 u_1' + m_1^2 u_1 \right) \right) e^{m_1 X} \\ + \left(u_2 - Q \left(u_2'' + 2m_2 u_2' + m_2^2 u_2 \right) \right) e^{m_2 X} \\ + \left(u_3 - Q \left(u_3'' + 2m_3 u_3' + m_3^2 u_3 \right) \right) e^{m_3 X} \\ + \left(u_4 - Q \left(u_4'' + 2m_4 u_4' + m_4^2 u_4 \right) \right) e^{m_4 X} \\ - Q * u_5 \left(\pi^2 x \cos(\pi x) - 2\pi \sin(\pi x) \right) \\ - Q \left(2\pi u_6' x \cos(\pi x) + \left(u_6'' - \pi^2 u_6 \right) \sin(\pi x) \right) \end{cases}$$
(17)

where

$$\begin{split} u_1 &= -3x\phi_1 - 6\phi_7 + x\Omega^4\phi_{13} - c_{01} \left(3x^2m_1^4 + 12xm_1^3 + 6m_1^2 \right) \\ u_2 &= -3x\phi_2 - 6\phi_8 + x\Omega^4\phi_{14} - c_{02} \left(3x^2m_2^4 + 12xm_2^3 + 6m_2^2 \right) \\ u_3 &= -3x\phi_3 - 6\phi_9 + x\Omega^4\phi_{15} - c_{03} \left(3x^2m_3^4 + 12xm_3^3 + 6m_3^2 \right) \\ u_4 &= -3x\phi_4 - 6\phi_{10} + x\Omega^4\phi_{16} - c_{04} \left(3x^2m_4^4 + 12xm_4^3 + 6m_4^2 \right) \\ u_5 &= -3\phi_5 - 6\phi_{11} + \Omega^4\phi_{17} + \frac{12\pi^3 P_o}{4} \\ u_6 &= -3\phi_6 - 6\phi_{12} + \Omega^4\phi_{18} + \frac{12\pi^3 P_o}{4} \\ \phi_1 &= m_1^4\phi_{13} + c_{11} \left(4m_1^3f_1' + 6f_1'' \right) \\ \phi_2 &= m_2^4\phi_{14} + c_{12} \left(4m_3^3f_3' + 6f_3'' \right) \\ \phi_3 &= m_3^4\phi_{15} + c_{13} \left(4m_3^3f_3' + 6f_3'' \right) \\ \phi_4 &= m_4^4\phi_{16} + c_{14} \left(4m_4^3f_4' + 6f_4'' \right) \\ \phi_5 &= \pi^4 f_5 - 4\pi^3 f_6 \\ \phi_6 &= \pi^4 f_6 \\ \phi_7 &= m_1^3\phi_{13} + 3c_{11} \left(m_1^2f_1' + m_1f_1'' \right) \\ \phi_8 &= m_2^3\phi_{14} + 3c_{12} \left(m_2^2f_2' + m_2f_2'' \right) \\ \phi_9 &= m_3^3\phi_{15} + 3c_{13} \left(m_3^2f_3' + m_3f_3'' \right) \\ \phi_{11} &= -\pi^3 f_6 \\ \phi_{12} &= \pi^3 f_5 - 3\pi^2 f_6 \end{split}$$

$$W_{3p} = T_1 \left[e^{m_1 X} G_1 + e^{-m_1 X} G_2 + e^{m_2 X} G_3 + e^{-m_2 X} G_4 \right] + Re \left(e^{i\pi X} T_1 G_5 \right) + Im \left(e^{i\pi X} T_1 G_6 \right) + Re \left(e^{i\pi X} T_1 G_7 \right) + Im \left(e^{i\pi X} T_1 G_8 \right) + Im \left(e^{i\pi X} T_1 G_9 \right)$$
(18)

$$\begin{split} T_1 &= \alpha_1 \Big(1 - \alpha_2 (D + m_1)^2 + \alpha_3 (D + m_1)^4 \Big), \alpha_1 = \frac{1}{K - \Omega^4} \\ G_1 &= F_1 \psi_1 + F_2 \phi_{13} + F_2 c_{01}, G_2 = F_4 \psi_2 + F_5 \phi_{14} + F_6 c_{02} \\ G_3 &= F_7 \psi_3 + F_8 \phi_{15} + F_9 c_{03}, G_4 = F_{10} \psi_4 + F_{11} \phi_{16} + F_{12} c_{04} \\ G_5 &= F_{13} \psi_5, G_6 = F_{13} \psi_6, G_7 = F_{14} \phi_{17}, G_8 = F_{14} \phi_{18} \\ G_5 &= \frac{P_o}{\pi^4 - Q \pi^2 + (K - \Omega^4)} F_{15} \\ F_1 &= -3X (D + m_1)^4 - 6(D + m_1)^3 + \Omega^4 X \\ F_2 &= -3X^2 (D + m_1)^4 - 12X (D + m_1)^3 - 6(D + m_1)^3 \\ F_3 &= -X^3 (D + m_1)^4 - 6X^2 (D + m_1)^3 - 6X (D + m_1)^3 \\ F_4 &= -3X (D - m_1)^4 - 6(D - m_1)^3 + \Omega^4 X \\ F_5 &= -3X^2 (D - m_1)^4 - 12X (D - m_1)^3 - 6(D - m_1)^3 \\ F_6 &= -X^3 (D - m_1)^4 - 6X^2 (D - m_1)^3 - 6X (D - m_1)^3 \\ F_7 &= -3X (D + m_2)^4 - 6(D + m_2)^3 + \Omega^4 X \\ F_8 &= -3X^2 (D + m_2)^4 - 6X^2 (D + m_2)^3 - 6X (D + m_2)^3 \\ F_{10} &= -3X (D - m_2)^4 - 6X^2 (D - m_2)^3 - 6X (D - m_2)^3 \\ F_{12} &= -X^3 (D - m_2)^4 - 6X^2 (D - m_2)^3 - 6X (D - m_2)^3 \\ F_{13} &= -3X (D + i\pi)^4 - 6X^2 (D - m_2)^3 - 6X (D - m_2)^3 \\ F_{14} &= -3X^2 (D + i\pi)^4 - 12X (D + i\pi)^3 - 6X (D + m_2)^3 \\ F_{15} &= -X^3 (D + i\pi)^4 - 6X^2 (D + i\pi)^3 - 6X (D + i\pi)^3 \\ \end{array}$$

The total non-dimensional lateral deflection is:

$$W = W_{\rm o} + \varepsilon W_1 + \varepsilon^2 W_2 + \varepsilon^3 W_3 + \cdots$$
(18)

The natural frequency and buckling load can be calculated as:

For a free non-prismatic beam on elastic foundation:

$$m_1 = m_2 = \pm i\beta_\Omega, m_3 = m_4 = \pm\beta_\Omega, \beta_\Omega^4 = \Omega^4 - K$$
(19)

For a non-prismatic beam subjected to axial load:

$$m_1 = m_2 = 0, m_3 = m_4 = \pm i\beta_Q, \beta^2 = Q$$

Applying the boundary conditions to obtain four linear equations in the constants $C_{i1}, C_{i2}, C_{i3}, C_{i4}$ in the form of:

$$[G]_{4*4}[C]_{4*1} = 0 \tag{20}$$

To have a non-trivial solution of Eq. (20), determinant of $[G]_{4*4}$ must be equal to zero. This will lead

the critical value of β , and then, we can find the nondimensional frequency and buckling load parameters for non-prismatic beam as

$$\Omega = \Omega_{\rm o} \left(1 + \varepsilon + \epsilon^2 + \epsilon^3 \right)^{1/4} \quad \text{Rectangular} \qquad (21)$$

$$\Omega = \Omega_{\rm o} \left(1 + \varepsilon + \epsilon^2 + \epsilon^3 + \epsilon^4 \right)^{1/4} \quad \text{Circular} \quad (22)$$

$$Q = Q_{\rm o} \left(1 + \varepsilon + \epsilon^2 + \epsilon^3 \right) \quad \text{Rectangular} \tag{23}$$

$$Q = Q_{\rm o} \left(1 + \varepsilon + \epsilon^2 + \epsilon^3 + \epsilon^4 \right) \quad \text{Circular} \tag{24}$$

where Ω_0 and Q_0 are the non-dimensional frequency and buckling load parameters for uniform beam.

2.2 Differential quadrature method (DQM)

The DQM requires to divide the domain of the problem into N pointes. Then, the derivatives at any point are approximated by a weighted linear summation of all the functional values along the domain, as follows [14-16]:

$$f_x(x_i) = \left. \frac{\mathrm{d}f}{\mathrm{d}x} \right|_{x_i} = \sum_{j=1}^N A_{ij} \cdot f\left(x_j\right), \quad i = 1, 2, \dots, N$$
(25)

where A_{ij} represented the weighting coefficient and N is the number of grid points in the whole domain. The weighting coefficient can be determined by making use of Lagrange formula as follows:

$$g_k(x) = \frac{M(x)}{(x - x_k) \cdot M^{(1)}(x_k)}, \quad k = 1, 2, \dots N$$
 (26)

where

$$M(x) = (x - x_1)(x - x_2) \dots (x - x_N)$$
(27)

$$M^{(1)}(x_i) = \prod_{k=1,k\neq i}^{N} (x_i - x_N)$$
(28)

By applying Eq. (28) at N grid points, the following algebraic formulations to compute the weighting coefficients A_{ii} can be obtained.

$$A_{ij} = \frac{1}{x_i - x_j} \prod_{k=1, k \neq i, j}^{N} \frac{(x_i - x_k)}{(x_j - x_k)}, \quad j \neq i$$
(29)

Table 1 Comparison between present DQM, PM, and analytical values for the first three non-dimensional frequencies of uniform beams

Non-dimensional frequency	Ω1	Ω2	Ω3
Analytical (C-C)	4.730	7.853	10.996
DQM (C-C)	4.730	7.853	10.996
PM (C-C)	4.730	7.853	10.996
Analytical (C-S)	3.927	7.069	10.210
DQM (C-S)	3.927	7.069	10.210
PM (C-S)	3.927	7.069	10.210

Table 2 Comparison between DQM and numerical values forthe first three non-dimensional frequencies of non-uniformbeams

Non-dimensional frequency $S(X) = (1 + \gamma X)$	Ω1	Ω2	Ω3
DQM (C-S), $\gamma = -1$	3.277	5.631	8.080
Du et al. [11] (C-S), $\gamma = -1$	3.277	5.630	8.082
DQM (C-S), $\gamma = 0.5$	4.124	7.451	10.737
Du et al. [11] (C-S), $\gamma = 0.5$	4.114	7.444	10.746

$$A_{ii} = \sum_{k=1, k \neq i}^{N} \frac{1}{x_i - x_k}$$
(30)

For calculating the weighting coefficients of *m*th order

$$\begin{bmatrix} A^{(m)} \end{bmatrix} = \begin{bmatrix} A^{(1)} \end{bmatrix} \cdot \begin{bmatrix} A^{(m-1)} \end{bmatrix}$$

=
$$\begin{bmatrix} A^{(m-1)} \end{bmatrix} \cdot \begin{bmatrix} A^{(1)} \end{bmatrix} \quad m = 2, 3, \dots, N-1$$
 (31)

The accuracy of DQM is affected by choosing of the number, N, and type of the sampling points, x_i . The optimal selection of the sampling points in the vibration problems, is the normalized Gauss–Chebyshev–Lobatto points [12, 13],

$$X(i) = \frac{1}{2} \left[1 - \cos\left(\frac{i-1}{N-1}\pi\right) \right], \quad i = 1, 2, 3, \dots, N$$
(32)

Applying the DQM scheme to the non-dimensional governing Eq. (8) yields:

$$S(X_{i})\left(\sum_{j=1}^{N} C_{ij}^{(4)} W_{j}\right) + 2 * S^{(1)}(X_{i})\left(\sum_{j=1}^{N} C_{ij}^{(3)} W_{j}\right)$$
$$+ S^{(2)}(X_{i})\left(\sum_{j=1}^{N} C_{ij}^{(2)} W_{j}\right) + Q\left(\sum_{j=1}^{N} C_{ij}^{(2)} W_{j}\right)$$
$$+ \left(K - \Omega^{4}\right)W_{i} = P(X_{i}) \quad i = 1, 2, 3, \dots, N$$
(33)

where W_i is the functional value at the grid points X_i , $C_{ij}^{(2)}$, $C_{ij}^{(3)}$ and $C_{ij}^{(4)}$ are the weighting coefficient matrices of the

Table 3 Results of PM and DQM for the non-dimensional frequencies of clamped-clamped non-prismatic rectangular beam

Non-dimensional frequency	$\gamma = 0$	$\gamma = 0.2$	$\gamma = 0.4$	$\gamma = 0.6$	$\gamma = 0.8$	$\gamma = 1$
PM (C-C), Ω1	4.730	4.999	5.340	5.745	6.200	6.689
DQM (C-C), Ω1	4.730	5.002	5.385	5.983	6.952	8.428
PM (C-C), Ω2	7.853	8.300	8.865	9.538	10.294	11.106
DQM (C-C), Ω2	7.853	8.305	8.940	9.933	11.542	13.992
PM (C-C), Ω3	10.996	11.622	12.413	13.355	14.413	15.551
DQM (C-C), Ω3	10.996	11.628	12.518	13.909	16.161	19.593

Table 4 Results of PM and DQM for the non-dimensional frequencies of clamped-clamped non-prismatic circular beam

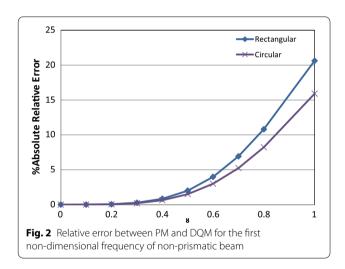
Non-dimensional frequency	$\gamma = 0$	$\gamma = 0.2$	$\gamma = 0.4$	$\gamma = 0.6$	$\gamma = 0.8$	$\gamma = 1$
PM (C-C), Ω1	4.730	5.001	5.361	5.829	6.405	7.073
DQM (C-C), Ω1	4.730	5.003	5.394	6.009	6.979	8.411
PM (C-C), Ω2	7.853	8.303	8.900	9.677	10.633	11.743
DQM (C-C), Ω2	7.853	8.306	8.956	9.976	11.586	13.965
PM (C-C), Ω3	10.996	11.626	12.462	13.550	14.889	16.443
DQM (C-C), Ω3	10.996	11.631	12.541	13.969	16.224	19.554

Non-dimensional buckling parameter	$\gamma = 0$	$\gamma = 0.2$	$\gamma = 0.4$	$\gamma = 0.6$	$\gamma = 0.8$	$\gamma = 1$
PM (C-C), Q1	39.478	49.269	64.113	85.905	116.540	157.914
DQM (C-C), Q1	39.478	49.295	64.655	89.466	130.670	198.959
PM (C-C), Q2	88.826	110.855	144.254	193.286	262.216	355.306
DQM (C-C), Q2	88.826	110.914	145.475	201.300	294.007	447.657
PM (C-C), Q3	157.914	197.076	256.452	343.620	466.161	631.655
DQM (C-C), Q3	157.914	197.181	258.622	357.866	522.679	795.835

Table 5 Comparison between PM and DQM for the non-dimensional buckling parameter of clamped–clamped non-prismatic rectangular beam

Table 6 Results of DQM and PM for the non-dimensional buckling parameter of clamped-clamped non-prismatic circular beam

Non-dimensional buckling parameter	$\gamma = 0$	$\gamma = 0.2$	$\gamma = 0.4$	$\gamma = 0.6$	$\gamma = 0.8$	$\gamma = 1$
PM (C-C), Q1	39.478	49.332	65.124	91.021	132.711	197.392
DQM (C-C), Q1	39.478	49.352	65.536	93.837	144.604	234.740
PM (C-C), Q2	88.826	110.998	146.528	204.798	298.599	444.132
DQM (C-C), Q2	88.826	111.042	147.457	211.134	325.359	528.165
PM (C-C), Q3	157.914	197.329	260.494	364.086	530.843	789.568
DQM (C-C), Q3	157.914	197.408	262.146	375.349	578.415	938.960



second-, third- and fourth-order derivatives. The result is a linear system of equations of N unknowns that can be written in a matrix form as

$$[G_o]_{N*N}[w]_{N*1} = \lambda [R_o]_{N*N}[w]_{N*1}$$
(34)

Four boundary conditions are needed to solve the problem. For clamped and simply supported end conditions, the discrete boundary conditions using the DQM can be written as:

$$W_1 = 0$$
 (35)

$$\sum_{k=1}^{N} C_{1,k}^{(n_0)} \cdot W_k = 0 \tag{36}$$

$$W_N = 0 \tag{37}$$

$$\sum_{k=1}^{N} C_{N,k}^{(n_1)} \cdot W_k = 0 \tag{38}$$

where n_0 , n_1 may be taken either 1 or 2; value of 1 represents simply supported and value of 2 represents clamped end. the boundary condition can be written in a matrix form as

$$[G_1]_{4*N}[w]_{N*1} = [R_1]_{4*N}[w]_{N*1}$$
(39)

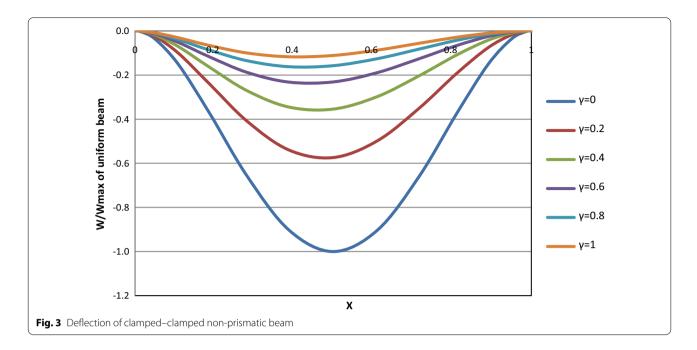
Combining governing Eqs. (33) and boundary conditions (34), we get

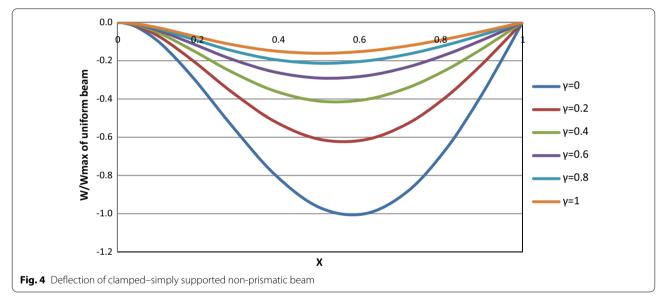
$$\begin{bmatrix} [G_{0}]_{N*N} \\ [G_{1}]_{4*N} \end{bmatrix} [w]_{N*1} = \upsilon \begin{bmatrix} [R_{0}]_{N*N} \\ [R_{1}]_{4*N} \end{bmatrix} [w]_{N*1}$$
(40)

; introducing the Lagrange multiplier approach [17], Eq. (40) can be modified to square matrix as

$$\begin{bmatrix} \begin{bmatrix} G_{0} \\ \begin{bmatrix} G_{1} \end{bmatrix}^{T} \\ 0 \end{bmatrix}_{(N+4)*(N+4)} \begin{bmatrix} w \\ l \end{bmatrix}_{(N+4)*1}$$

$$= \upsilon \begin{bmatrix} \begin{bmatrix} R_{0} \end{bmatrix} \begin{bmatrix} R_{1} \end{bmatrix}^{T} \\ \begin{bmatrix} R_{1} \end{bmatrix}_{(N+4)*(N+4)} \begin{bmatrix} w \\ l \end{bmatrix}_{(N+4)*1}$$
(41)





where l is the Lagrange multiplier and v is the Eigenvalue to be obtained. Rewrite Eq. (41) in the form

$$\begin{bmatrix} \begin{bmatrix} G_0 \end{bmatrix} \begin{bmatrix} G_1 \end{bmatrix}^T \\ \begin{bmatrix} G_1 \end{bmatrix} \begin{bmatrix} R_0 \end{bmatrix} \begin{bmatrix} R_1 \end{bmatrix}^T \\ \begin{bmatrix} R_1 \end{bmatrix} = \gamma \begin{bmatrix} w \\ l \end{bmatrix}$$
(42)

Solve the Eigen-value problem in Eq. (42) to find nondimensional frequency parameter and non-dimensional buckling load parameter. This approach can be used to easily implement any boundary condition without modifying weighting coefficients of the DQM.

3 Results

3.1 Verification for prismatic beams

The present PM and DQM results for uniform beam with different end support, listed in Table 1, are identical as compared with the analytical solution in [15]. It is clear that there is a very good agreement between the present results and the previous analytic solution for uniform beam. On the other hand, the results of non-dimensional frequency obtained from the present DQM for non-uniform beam, listed in Table 2, are compared to numerical values obtained in [11] giving a good agreement with error less than 0.5%.

3.2 Results of vibration parameters for non-prismatic beams

The DQM is applied with different numbers of grid points. The optimum number of grid points is found to be 15 points. After 15 grid points, the results of DQM are fixed [16]. The DQM showed good ability for the analysis of non-prismatic beam with different end supports. The results of non-dimensional frequency and buckling parameters are obtained using the present PM and DQM for clamped–clamped ends, and different values of γ are presented in Tables 3, 4, 5 and 6. The results showed agreement between results for < 0.6. If $\gamma = 1$, the relative error reached about 20%. The accuracy of the PM depends on the value of γ , so as γ increases, the effect of neglected terms affects the results of PM.

Figure 2 presents the percentage relative error between the PM and DQM for the first non-dimensional frequency of non-prismatic beam calculated by the following equation:

%Absolute relative error =
$$\left| \frac{\Omega_{DQM} - \Omega_{PM}}{\Omega_{DQM}} \right| \times 100$$

3.3 Deflection for non-prismatic beams

The deflection of non-prismatic beam with circular cross section under the effect of constant vertical load is plotted for two different cases of end supports and different values of γ as shown in Figs. 3 and 4. As γ increases, the maximum deflection decreases and the location of maximum deflection displaced toward the smaller moment of inertia as predicted.

4 Discussion

Results of DQM and PM for uniform beams, as shown in Table 1, showed perfect agreement with analytical solution for non-dimensional frequency parameter. DQM results for non-uniform beams, as shown in Table 2, proved its perfect ability in prediction of non-dimensional frequency parameter as compared with numerical results given in [11]. The error for listed cases is less than 0.1%. Good results of DQM required fifteen discretization points.

Both methods are used to predict non-dimensional frequency and buckling parameters for non-uniform beams with rectangular or circular cross sections, as shown in Tables 3, 4, 5 and 6. All cases have clamped–clamped ends. The results showed good ability of PM in prediction of non-dimensional frequency and non-dimensional buckling load when the height or the radius increasing ratios are less than 60%. The results of PM are not reliable for higher increasing ratio of height or radius. Deflection results for clamped-clamped (Fig. 3), clamped-simply supported (Fig. 4), non-uniform beams subjected to a constant uniform load showed good ability of PM in prediction of lateral deflection and the effect of radius increasing ratio on the location of maximum lateral deflection along the beam length. As the increasing ratio of radius increases, the location of maximum lateral deflection moves toward the position of maximum height. Maximum deflection decreases as the increasing ratio of radius increases.

5 Conclusions

The present paper presents two mathematical techniques to investigate the buckling load as well as the natural frequency under axial and transverse load for non-prismatic beams. The deflection of the beam resting on an elastic foundation under transverse distributed and axial loads is also obtained for different end supports. From the present study, the following points could be concluded:

- The PM and DQM succeeded powerfully for investigating the buckling load as well as the natural frequency for non-prismatic beam.
- The percentage of relative error between DQM and PM doesn't exceed than 5% for γ < 0.6.
- As γ increases, the maximum deflection decreases and the location of maximum deflection displaced toward the smaller moment of inertia.

Abbreviations

PM: Perturbation method; DQM: Differential quadrature method.

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Authors' contributions

MA team leader who initiates the concept of the paper derived the governing equations. SA performed the analytical solution by perturbation method. ME applied the numerical method of differential quadrature and wrote the manuscript. All authors have read and approved the manuscript.

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Consent for publication

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Competing interests

The authors declare no competing interest.

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